

# Math 240 Quiz 3 (1.7-1.9)

NetID: \_\_\_\_\_

Class time: \_\_\_\_\_

**Instructions:** Calculators, course notes and textbooks are **NOT** allowed on the quiz. All numerical answers **MUST** be exact; e.g., you should write  $\pi$  instead of 3.14...,  $\sqrt{2}$  instead of 1.414..., and  $\frac{1}{3}$  instead of 0.3333... Explain your reasoning using complete sentences and correct grammar, spelling, and punctuation.

**Show ALL of your work!**

You have 20 minutes.

**Question 1** (6 points). True or false? If true, please explain. If false, construct a counterexample.

- (i) Let  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear transformation. If the vectors  $\mathbf{v}_1, \dots, \mathbf{v}_k$  are linearly independent in  $\mathbb{R}^n$ , then so are  $T(\mathbf{v}_1), \dots, T(\mathbf{v}_k)$  in  $\mathbb{R}^m$ .

False. Let  $T$  be the linear transformation that sends everything to the zero vector.

(The converse is true. If  $T(\vec{v}_1), \dots, T(\vec{v}_k)$  are linearly independent, then

$$c_1 \vec{v}_1 + \dots + c_k \vec{v}_k = \vec{0} \implies T(c_1 \vec{v}_1 + \dots + c_k \vec{v}_k) = \vec{0}$$

$$\stackrel{\text{linearity}}{\implies} c_1 T(\vec{v}_1) + \dots + c_k T(\vec{v}_k) = \vec{0}$$

$$\stackrel{\text{independency}}{\implies} c_1 = \dots = c_k = 0, \text{ which means}$$

- (ii) Given an  $m \times n$  matrix  $A$  with  $m > n$ , the transformation  $\mathbf{x} \mapsto A\mathbf{x}$  cannot be one-to-one.

False. This transformation is one-to-one precisely when the matrix equation  $A\vec{x} = \vec{b}$

has at most one solution for each  $\vec{b}$  in  $\mathbb{R}^m$ .

This means that the homogeneous equation

$A\vec{x} = \vec{0}$  has only the trivial solution. Let

$$A = \begin{bmatrix} 1 & & & 0 \\ & 1 & & \\ & & \ddots & \\ 0 & & & 1 \\ & & & & * \end{bmatrix}$$

$\vec{v}_1, \dots, \vec{v}_k$  are linearly independent.)

**Question 2** (4 points). Let  $T(x_1, x_2) = (3x_1 + x_2, x_1 + h)$  be a transformation from  $\mathbb{R}^2$  to itself.

(i) Determine the values of  $h$  for which  $T$  is onto.

For each  $\vec{b} = (b_1, b_2)$  in  $\mathbb{R}^2$ , we need that

$$\begin{cases} 3x_1 + x_2 = b_1 \\ x_1 + h = b_2 \end{cases}$$

has a solution. Simply take  $\begin{cases} x_1 = b_2 - h \\ x_2 = b_1 - 3(b_2 - h) \end{cases}$ .

Thus any value of  $h$  makes  $T$  onto.

(ii) Determine the values of  $h$  for which  $T$  is a linear transformation. Find its standard matrix in this case.

Given  $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  and  $\vec{x}' = \begin{bmatrix} x_1' \\ x_2' \end{bmatrix}$ , we need

$$T(\vec{x} + \vec{x}') = T(\vec{x}) + T(\vec{x}')$$

Comparing the second components on both sides

$$x_1 + x_1' + h = (x_1 + h) + (x_1' + h)$$

forces  $h = 0$ . The transformation  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \mapsto \begin{bmatrix} 3x_1 + x_2 \\ x_1 \end{bmatrix} = \begin{bmatrix} 3 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

is linear, with standard matrix  $\begin{bmatrix} 3 & 1 \\ 1 & 0 \end{bmatrix}$ .