

## Change of bases and similarity of matrices

Recall Given a basis  $\mathcal{U} = \{\vec{u}_1, \dots, \vec{u}_n\}$  of  $\mathbb{R}^n$ , for any vector  $\vec{x}$  in  $\mathbb{R}^n$ , the coordinates of  $\vec{x}$  with respect to  $\mathcal{U}$  are the weights that appear in the unique expression of  $\vec{x}$  as a linear combination of  $\vec{u}_1, \dots, \vec{u}_n$ :

$$\vec{x} = x_1 \vec{u}_1 + \dots + x_n \vec{u}_n$$

They give a column vector denoted by  $[\vec{x}]_{\mathcal{U}}$

$$[\vec{x}]_{\mathcal{U}} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

Given a linear transformation  $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ , the matrix  $A$  that represents  $T$  with respect to  $\mathcal{U}$  is given by

$$A = \begin{bmatrix} [T(\vec{u}_1)]_{\mathcal{U}} & \dots & [T(\vec{u}_n)]_{\mathcal{U}} \end{bmatrix}$$

so that

$$\begin{aligned} [T(\vec{x})]_{\mathcal{U}} &= [T([\vec{u}_1 \dots \vec{u}_n][\vec{x}]_{\mathcal{U}})]_{\mathcal{U}} \\ &= [ [T(\vec{u}_1) \dots T(\vec{u}_n)] [\vec{x}]_{\mathcal{U}} ]_{\mathcal{U}} \\ &= [ [T(\vec{u}_1)]_{\mathcal{U}} \dots [T(\vec{u}_n)]_{\mathcal{U}} ] [\vec{x}]_{\mathcal{U}} \\ &= A [\vec{x}]_{\mathcal{U}} \end{aligned}$$

(This generalizes the standard matrix of  $T$ , where the underlying basis is the standard basis  $\{\vec{e}_1, \dots, \vec{e}_n\}$ .)

Now Let  $\mathcal{V} = \{\vec{v}_1, \dots, \vec{v}_n\}$  be another basis, with

$$[\vec{v}_1 \dots \vec{v}_n] = [\vec{u}_1 \dots \vec{u}_n] C$$

for some invertible  $C$ . Let  $B$  be the matrix that represents  $T$  with respect to  $\mathcal{V}$ .

Claim The matrices  $A$  and  $B$  are similar;  $B = C^{-1} A C$

Proof Since  $\vec{x} = [\vec{u}_1 \dots \vec{u}_n] [\vec{x}]_{\mathcal{U}}$

$$= [\vec{v}_1 \dots \vec{v}_n] C^{-1} [\vec{x}]_{\mathcal{U}}$$

we have  $[\vec{x}]_{\mathcal{V}} = C^{-1} [\vec{x}]_{\mathcal{U}}$  (by uniqueness of the coordinates with respect to  $\mathcal{V}$ ). Thus

$$\begin{aligned} B &= \begin{bmatrix} [T(\vec{v}_1)]_{\mathcal{V}} & \dots & [T(\vec{v}_n)]_{\mathcal{V}} \end{bmatrix} \\ &= \begin{bmatrix} C^{-1} [T(\vec{v}_1)]_{\mathcal{U}} & \dots & C^{-1} [T(\vec{v}_n)]_{\mathcal{U}} \end{bmatrix} \\ &= C^{-1} \begin{bmatrix} [T(\vec{v}_1)]_{\mathcal{U}} & \dots & [T(\vec{v}_n)]_{\mathcal{U}} \end{bmatrix} \\ &= C^{-1} \begin{bmatrix} [T(\vec{u}_1)]_{\mathcal{U}} & \dots & [T(\vec{u}_n)]_{\mathcal{U}} \end{bmatrix} C \\ &= C^{-1} A C \end{aligned}$$